Ordinary Differential Equations (Ode's)

We shall consider some numerical schemes to solve initial-value problems (Cauchy's problems) written as: Find $y = y(t)$ solution of

$$
\begin{cases}\ny'(t) = f(t, y(t)) & t \in [t_0, T] \\
y(t_0) = y_0.\n\end{cases}
$$
\n(1)

We assume $\mathcal{y} : [t_0, T] \to \mathbb{R}$ but can be generalized to $\mathcal{y} : [t_0, T] \to \mathbb{R}^d$

In general $f(t, y(t))$ is a non-linear function describing the evolution in time of $y(t)$. The true solution $y(t)$ of [\(1\)](#page-0-0) evolves continuously in time, and we want to follow it by a discrete approximation.

Both exact and discrete solution of [\(1\)](#page-0-0) start from the same initial value y_0 at t₀. The discrete one takes finite steps Δt , and after *n* steps it reaches a value y_n . We hope and expect that y_n is close to the exact value $y(t_0 + n\Delta t)$. We shall see that this may or may not happen.

Numerical methods for Ode's

Let us see some schemes to solve numerically [\(1\)](#page-0-0). They are numerous, and a first distinction is among 1-step methods and multi-step methods. Let us see 1-step methods. They can all be derived in the following way. Le $t_0, t_1, \dots, t_N = T$ be a set of points in $[t_0, T]$; as usual, for simplify notation we take them equally spaced: (N given, we define $\Delta t = \frac{T-t_0}{N}$ N and we set $t_0, t_1 = t_0 + \Delta t, t_2 = t_1 + \Delta t, \dots, t_N = T$. At each step, (on each subinterval $[t_n,t_{n+1}]$) we integrate the differential equations...

$$
y'(t) = f(t,y(t))
$$

$$
y(t_{n+1}) - y(t_n) = \int_{t_n}^{t_{n+1}} y'(t) dt = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt.
$$
 (*)

Then, as $y(t)$ in the interval $[t_n,t_{n+1}]$ is unknown to us (and moreover, in general, we are unable to compute the integral exactly), we use some quadrature formula.

$$
y(t_{n+1}) - y(t_n) = \int_{t_n}^{t_{n+1}} y'(t) dt = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt.
$$
 (*)

$$
\int_{t_n}^{t_{n+1}} f(t,y(t))dt \sim \text{ quadrature formula.}
$$

Different choices of quadrature formulas give rise to different schemes.

Example 1 We consider first the quadrature formula

$$
\int_{c}^{d} g(s)ds \simeq (d-c) g(c) \tag{2}
$$

that, indeed, is very poor (and is exact only for $g = constant$). Then

$$
\int_{t_n}^{t_{n+1}} f(t,y(t)) dt \simeq (t_{n+1}-t_n) f(t_n,y(t_n)) \quad n=0,1,2,\cdots \quad (3)
$$

Using [\(3\)](#page-3-0) into $y(t_{n+1}) - y(t_n) = \int_{t_n}^{t_{n+1}} y'(t) dt = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt$ we get:

$$
y(t_1) \simeq y(t_0) + \Delta t f(t_0, y(t_0)) = y_0 + \Delta t f(t_0, y_0) =: y_1
$$

\n
$$
y(t_2) \simeq y(t_1) + \Delta t f(t_1, y(t_1)) \simeq y_1 + \Delta t f(t_1, y_1) =: y_2
$$

\n:
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$$
y(t_N) \simeq y(t_{N-1}) + \Delta t f(t_{N-1}, y(t_{N-1})) \simeq y_{N-1} + \Delta t f(t_{N-1}, y_{N-1}) =: y_N
$$

It is clear from this that errors accumulate at each step and might produce unexpected results. We will analyse the scheme later on. Let us write it in a compact form:

> $\int y_0$ given $y_{n+1} = y_n + \Delta t f(t_n, y_n)$ $n = 0, 1, \cdots, N-1$ (EE)

This is called EXPLICIT EULER method or FORWARD EULER method: at each step, the value y_n can be explicitly computed using values at the previous steps. It is very simple and inexpensive but, as we shall see, there is a "but" \ldots

. . .

Example 2 This time we consider the quadrature formula

$$
\int_{c}^{d} g(s)ds \simeq (d-c) g(d) \tag{4}
$$

that is also very poor and is exact only if $g = constant$, like the previous one. However the resulting scheme will be very different. In fact, applying it to our case we get

$$
\int_{t_n}^{t_{n+1}} f(t,y(t)) dt \simeq (t_{n+1}-t_n) f(t_{n+1},y(t_{n+1})) \quad n=0,1,2,\cdots
$$

that used into $y(t_{n+1}) - y(t_n) = \int_{t_n}^{t_{n+1}} y'(t) dt = \int_{t_n}^{t_{n+1}} f(t, y(t)) dt$ gives

$$
y(t_1) \simeq y(t_0) + \Delta t f(t_1, y(t_1)) \simeq y_0 + \Delta t f(t_1, y_1) =: y_1
$$

$$
y(t_2) \simeq y(t_1) + \Delta t f(t_2, y(t_2)) \simeq y_1 + \Delta t f(t_2, y_2) =: y_2
$$

 $y(t_N) \simeq y(t_{N-1}) + \Delta t f(t_N, y(t_N)) \simeq y_{N-1} + \Delta t f(t_N, y_N) =: y_N$

The scheme becomes

$$
\begin{cases}\ny_0 \text{ given} \\
y_{n+1} = y_n + \Delta t f(t_{n+1}, y_{n+1}) & n = 0, 1, \cdots, N-1 \quad (IE)\n\end{cases}
$$

This is called IMPLICIT EULER method or BACKWARD EULER method. Note that, at every time step, the unknown y_{n+1} in (IE) appears both on the left-hand side and in the right-hand side, and in order to perform the step we must solve an equation in the unknown y_{n+1} . Since f is in general non-linear, at each step, to find y_n we need to solve a non-linear equation (for example, with Newton method). The method is obviously more expensive than Explicit Euler.

Example 3 As a third example we consider the quadrature formula

$$
\int_{c}^{d} g(s)ds \simeq (d-c)\left(\frac{g(c)+g(d)}{2}\right) \tag{5}
$$

(trapezoidal rule) that is better than the previous ones since it is exact whenever g is a polynomial of degree ≤ 1 . Applying it to our case we get

$$
\int_{t_n}^{t_{n+1}} f(t,y(t))dt \simeq \frac{(t_{n+1}-t_n)}{2} \Big(f(t_n,y(t_n)) + f(t_{n+1},y(t_{n+1})) \Big) \quad \forall n
$$

The corresponding scheme becomes

$$
\begin{cases}\ny_0 \text{ given} \\
y_{n+1} = y_n + \frac{\Delta t}{2} \Big(f(t_n, y_n) + f(t_{n+1}, y_{n+1}) \Big) & n = 0, 1, \cdots, N-1\n\end{cases}
$$

$$
\begin{cases}\ny_0 \text{ given} \\
y_{n+1} = y_n + \frac{\Delta t}{2} \Big(f(t_n, y_n) + f(t_{n+1}, y_{n+1}) \Big) & n = 0, 1, \cdots, N-1\n\end{cases}
$$

This is called CRANK-NICOLSON method. It is an implicit method (and hence, as the previous Implicit Euler, expensive) but it has a good accuracy, as we shall see.

Example 4 If we replace, in the Crank-Nicolson scheme, y_{n+1} with $y_{n+1}^* = y_n + \Delta t f(t_n, y_n)$, that is, with the value predicted by Explicit Euler, we get rid of the implicit part and obtain a new explicit method, called HEUN method, which reads

$$
\begin{cases}\ny_0 \text{ given} \\
y_{n+1}^* = y_n + \Delta t f(t_n, y_n) \\
y_{n+1} = y_n + \frac{\Delta t}{2} \Big(f(t_n, y_n) + f(t_{n+1}, y_{n+1}^*) \Big) & n = 0, 1, \cdots, N-1\n\end{cases}
$$

So we have two classes: explicit methods, and implicit methods. In all cases we want the sequence $\{y_0, y_1, \dots, y_N\}$ to converge to the sequence $\{y_0, y(t_1), \cdots, y(T)\}\.$

If, given a method, we can prove that

 $\exists C > 0$ such that $\max_{n} |y_n - y(t_n)| \leq C \Delta t^p$

with C independent of Δt and $p > 0$, then we say that the method is convergent, and the order of convergence is p (the bigger p , the faster the convergence).